

# Dynamical systems 2

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## **Quantitative Methods in Historical Linguistics**

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# First things first: About the Portfolio

- Remember: Portfolio deadline is **1ST AUGUST** (midnight)
- Please submit your Portfolio by email, as a **PDF ATTACHMENT** (only one PDF please)
  - If you need to put together multiple PDFs and don't know how, just ask me!
- Your Portfolio can contain hand-written parts (you'll have to scan them)
- Remember the marking criteria. To get full points,
  - 1 Your solutions need to work
  - 2 Your solutions must not be inelegant
- Remember to include all R code (and plots) needed to answer the portfolio questions. If vital parts (parts that are necessary for replicating your results) are missing, points will be deducted
- Any questions?

## From last time: A first model

- Assume a population of  $N$  speakers
- Assume that there is a binary variable of interest
  - e.g. do-support vs. no do-support
  - or final fortition vs. no final fortition
- Let's call one of these **VARIANTS**  $X$  and the other one  $Y$
- Assume that each speaker uses either  $X$  or  $Y$ , but not both
- Let's write  $x_t$  for the number of people using  $X$  at time  $t$  and  $y_t$  for the number of people using  $Y$  at time  $t$

## From last time: A first model

- Assume that we take a look at this population once every week
  - $x_0$  is the number of X-speakers initially
  - $x_1$  is the number of X-speakers after 1 week
  - $x_2$  is the number of X-speakers after 2 weeks
  - $\vdots$
  - $x_t$  is the number of X-speakers after  $t$  weeks
  - And similarly for  $y_t$
- Assume that, within one week, a proportion  $a$  of Y-speakers become X-speakers

### What we found out last time

It is possible to calculate  $x_{t+1}$  and  $y_{t+1}$  if we know the values of  $x_t$ ,  $y_t$  and  $a$

# Difference equations

- For example, if  $x_0 = 100$ ,  $y_0 = 200$  and  $a = 0.1$ , then

$$x_1 = \underbrace{100}_{=x_0} + \underbrace{0.1}_{=a} \times \underbrace{200}_{=y_0} = 100 + 20 = 120$$

and

$$y_1 = \underbrace{200}_{=y_0} - \underbrace{0.1}_{=a} \times \underbrace{200}_{=y_0} = 200 - 20 = 180$$

- From this, we can extract the general equations:

$$\begin{cases} x_{t+1} = x_t + ay_t \\ y_{t+1} = y_t - ay_t \end{cases} \quad (*)$$

- 'General' = valid for any time  $t$
- (\*) is a pair of **DIFFERENCE EQUATIONS** (from it you can figure out the difference between  $x_t$  and  $x_{t+1}$ , for example)

## Conservation of population size

- Let's look at our pair of difference equations in a bit more detail:

$$\begin{cases} x_{t+1} = x_t + ay_t \\ y_{t+1} = y_t - ay_t \end{cases}$$

- Observation: over any time step  $t \rightarrow t + 1$ ,  $ay_t$  is added to  $x_t$  and  $ay_t$  is subtracted from  $y_t$
- This means there is a **FLOW** from Y to X
  - The number of X-speakers should always increase
  - The number of Y-speakers should always decrease
- Moreover, population size stays constant under this flow
  - Look what happens if we calculate the total population size at time  $t + 1$ :

$$x_{t+1} + y_{t+1} = x_t + ay_t + y_t - ay_t = x_t + y_t$$

## The parameter $a$

- Recall that  $x_t$  and  $y_t$  are the only **VARIABLES** of this dynamical system
  - Variable of a dynamical system = something that depends on time,  $t$
- The number  $a$ , in contrast, is a **PARAMETER**
  - It does not depend on  $t$ , but rather always stays the same

### Reflection Exercise

- 1 Let's suppose  $a = 0.5$  rather than  $a = 0.1$  as previously. What happens?
- 2 What happens if  $a = 0.01$ ?
- 3 What happens if  $a = 0$ ?

## The parameter $a$

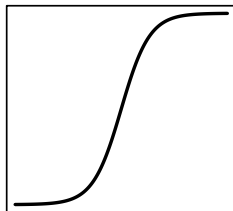
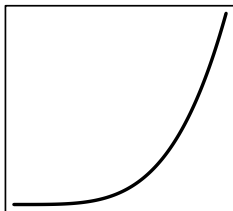
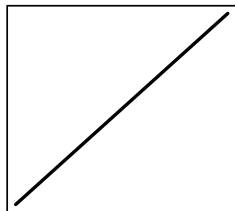
$$\begin{cases} x_{t+1} = x_t + ay_t \\ y_{t+1} = y_t - ay_t \end{cases}$$

- If  $a = 0.5$  instead of  $a = 0.1$ , the number of  $X$ -speakers grows 5 times faster
- If  $a = 0.01$  instead of  $a = 0.1$ , the number of  $X$ -speakers grows 10 times slower
- If  $a = 0$ , nothing happens: the number of  $X$ -speakers stays the same and the number of  $Y$ -speakers stays the same



## Time evolution

- So we know the number of X-speakers increases over time in this model
- But **HOW** exactly does it increase?



# Iterating a dynamical system with R

- We could calculate each  $x_t$  and  $y_t$  by hand/calculator
- But that gets very tedious... particularly if we want to do this for many **ITERATIONS** (time steps)
- Let's see how to use R for this purpose
- We need a new tool we haven't seen yet: a **LOOP**



[https://commons.wikimedia.org/wiki/File:Big\\_Loop\\_Ausschnitt,\\_Heide-Park.jpg](https://commons.wikimedia.org/wiki/File:Big_Loop_Ausschnitt,_Heide-Park.jpg)

# Loops

- With a **FOR-LOOP**, you can make R do something more than once
- Suppose we want to print the string "Dynamical systems are fun!" 10 times on the screen
- Use the following loop:

```
for (i in 1:10) {  
  print("Dynamical systems are fun!")  
}
```

- Try it for yourself!
- What happens here? The (temporary) variable *i* goes through each value in the vector 1:10. The `print` command is executed each time. When *i* has gone through all elements of 1:10, R exits the loop.

# Loops

- For-loops can be complicated, and they can refer to the value of `i` (which keeps changing as the loop is iterated):

```
for (i in c(1,2,3,5)) {  
  j <- 2*i  
  print(j)  
}
```

```
## [1] 2  
## [1] 4  
## [1] 6  
## [1] 10
```

- Can also be written in one line:

```
for (i in c(1,2,3,5)) { j <- 2*i; print(j) }
```

# Iterating a dynamical system with R

- Okay, back to the topic. First, we need to decide how many time steps we want. Let's do 100:

```
iterations <- 100
```

- Then we need vectors to hold values of  $x_t$  and  $y_t$ :

```
x <- rep(NA, length=iterations)
y <- rep(NA, length=iterations)
```

- Put the initial values in place. For example, let's do  $x_0 = 10$  and  $y_0 = 590$ :

```
x[1] <- 10
y[1] <- 590
```

- We also need a value of  $a$ . Let's stick to  $a = 0.1$ :

```
a <- 0.1
```

# Iterating a dynamical system with R

- Now the for loop:

```
for (t in 1:(iterations-1)) {  
  x[t+1] <- x[t] + a*y[t]  
  y[t+1] <- y[t] - a*y[t]  
}
```

- Note how this mirrors our difference equations:

$$\begin{cases} x_{t+1} = x_t + ay_t \\ y_{t+1} = y_t - ay_t \end{cases}$$

- The magic here is:  $x$  and  $y$  are both vectors, and  $t$  is used to index them. The  $(t + 1)$ th value of the  $x$  vector is calculated from the  $t$ th value of  $x$  and  $y$ , and similarly for  $y$ .

# Iterating a dynamical system with R

- It's best to put this in a function

```
first_model <- function(iterations, x0, y0, a) {  
  x <- rep(NA, length=iterations)  
  y <- rep(NA, length=iterations)  
  x[1] <- x0  
  y[1] <- y0  
  for (t in 1:(iterations-1)) {  
    x[t+1] <- x[t] + a*y[t]  
    y[t+1] <- y[t] - a*y[t]  
  }  
  times <- 0:(iterations-1)  
  data.frame(t=times, x=x, y=y)  
}
```

# Iterating a dynamical system with R

- Now we can use this function:

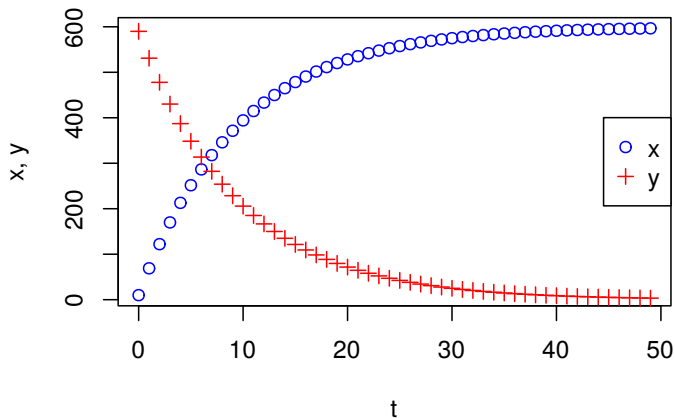
```
df <- first_model(iterations=50, x0=10, y0=590, a=0.1)
head(df)
```

```
##      t          x          y
## 1  0  10.0000  590.0000
## 2  1  69.0000  531.0000
## 3  2 122.1000  477.9000
## 4  3 169.8900  430.1100
## 5  4 212.9010  387.0990
## 6  5 251.6109  348.3891
```

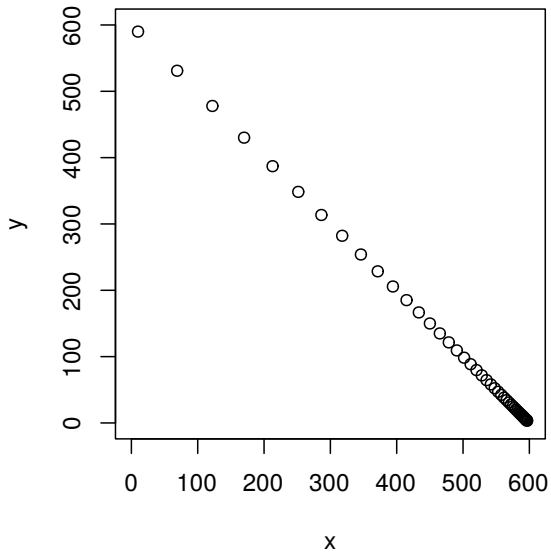


# Iterating a dynamical system with R

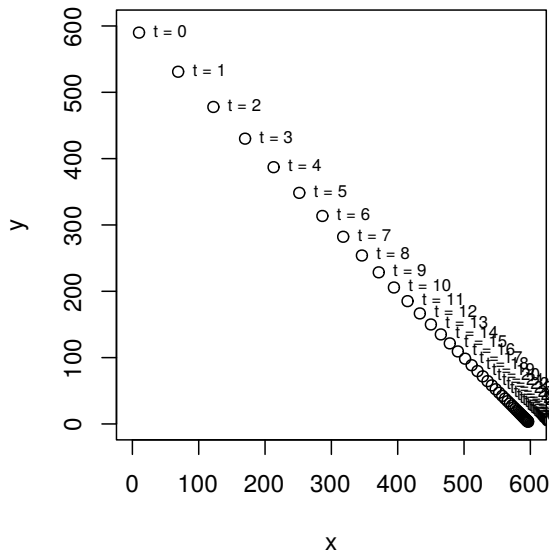
```
plot(df$t, df$x, xlab="t", ylab="x, y", col="blue")  
points(df$t, df$y, pch=3, col="red")  
legend("right", pch=c(1,3), col=c("blue", "red"),  
       legend=c("x", "y"))
```



# The state space



# The state space



# The state space

- This kind of plot is known as a **STATE SPACE PLOT**
- Making one is not difficult:

```
plot(df$x, df$y, xlim=c(0,600), ylim=c(0,600),  
      xlab="x", ylab="y")
```

- If you want the time labels, add the following command:

```
text(x=df$x, y=df$y, labels=paste("t =", df$t),  
      pos=4, cex=0.7)
```

- `text` puts labels at the specified `x` and `y` positions
- `pos=4` means labels should go to the right of the points
- `cex=0.7` ("character expansion") makes the text a bit smaller
- As always, use `?text` (or Google) to find out more

## A fixed point

- The state to which this system tends as  $t$  grows is given by the solution of the following equations:

$$\begin{cases} x_t = x_t + ay_t \\ y_t = y_t - ay_t \end{cases}$$

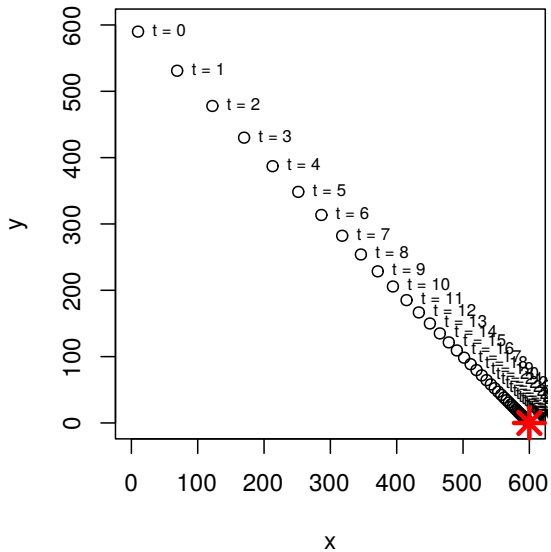
(i.e. we specify  $x_{t+1} = x_t$  and  $y_{t+1} = y_t$ )

- The only solution is  $x = N, y = 0$ :

$$\begin{cases} N = N + a \times 0 = N \\ 0 = 0 - a \times 0 = 0 \end{cases}$$

- The state  $x = N, y = 0$  is known as a **FIXED POINT** (or a **REST POINT**)
- This system has only one fixed point, but in general dynamical systems may have several fixed points

# A fixed point



## A second model: Two flows

- In reality, we'd expect some  $X$ -speakers to become  $Y$ -speakers, too, and not just vice versa
- I.e. we have two flows

### Reflection Exercise

Suppose

- $Y$ -speakers become  $X$ -speakers at a rate  $a$  (as before)
- $X$ -speakers become  $Y$ -speakers at a rate  $b$

What is the pair of difference equations for this extended model?

## A second model: Two flows

- The equations are:

$$\begin{cases} x_{t+1} = x_t + ay_t - bx_t \\ y_{t+1} = y_t - ay_t + bx_t \end{cases}$$

- Rearranging the terms a bit, we have:

$$\begin{cases} x_{t+1} = (1-b)x_t + ay_t \\ y_{t+1} = bx_t + (1-a)y_t \end{cases}$$

- The dynamics are now determined by  $a$  and  $b$
- Questions we must answer:

- 1 Which one increases,  $x_t$  or  $y_t$ ?
- 2 What are the eventual values of  $x_t$  and  $y_t$  (when  $t$  is large)?
- 3 What **SHAPE** do the dynamics take in the time dimension?



## Fixed point(s)

- So now we have the slightly more complicated pair of equations:

$$\begin{cases} x_{t+1} = (1 - b)x_t + ay_t \\ y_{t+1} = bx_t + (1 - a)y_t \end{cases}$$

- How to, first of all, figure out the fixed point(s) of this system?
- Insight: since population size is conserved, we always have  $y_t = N - x_t$
- So we only need one equation, really:

$$x_{t+1} = (1 - b)x_t + a \underbrace{(N - x_t)}_{=y_t}$$

## Fixed point(s)

- Need to solve this equation for  $x$  to get the fixed point(s):

$$x = (1 - b)x + a(N - x)$$

## Fixed point(s)

- Need to solve this equation for  $x$  to get the fixed point(s):

$$x = (1 - b)x + a(N - x)$$

- Let's go step by step:

$$x = x - bx + aN - ax$$

## Fixed point(s)

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$$x - aN = x - bx - ax$$

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$$aN = bx + ax$$

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$$aN = bx + ax$$

$$aN = (a + b)x$$

## Fixed point(s)

- Need to solve this equation for  $x$  to get the fixed point(s):

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- Let's go step by step:

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$$x - aN = x - bx - ax$$

$$-aN = -bx - ax$$

$$aN = bx + ax$$

$$aN = (a + b)x$$

$$(a + b)x = aN$$



## Fixed point(s)

- Need to solve this equation for  $x$  to get the fixed point(s):

$$x = (1 - b)x + a(N - x)$$

- Let's go step by step:

$$x = x - bx + aN - ax$$

$$x - aN = x - bx - ax$$

$$-aN = -bx - ax$$

$$aN = bx + ax$$

$$aN = (a + b)x$$

$$(a + b)x = aN$$

$$x = \frac{aN}{a + b}$$

## Fixed point(s)

- So again there is just one fixed point:

$$x = \frac{aN}{a+b}$$

- But this time its value depends on  $a$  and  $b$

### Reflection Exercise

- 1 What happens if  $b = 0$  (but  $a \neq 0$ )?
- 2 What happens if  $a = 0$  (but  $b \neq 0$ )?
- 3 What happens if  $a = b$  (but  $a, b \neq 0$ )?

## Fixed point(s)

- 1 If  $b = 0$  (but  $a \neq 0$ ):

$$x = \frac{aN}{a+b} = \frac{aN}{a} = N$$

We get the same fixed point we saw with the first model (makes sense!)

- 2 If  $a = 0$  (but  $b \neq 0$ ):

$$x = \frac{aN}{a+b} = \frac{0}{b} = 0$$

This is different. Also makes sense.

- 3 If  $a = b$  (but  $a, b \neq 0$ ):

$$x = \frac{aN}{a+b} = \frac{aN}{a+a} = \frac{aN}{2a} = \frac{N}{2}$$

If both transition rates  $X \rightarrow Y$  and  $Y \rightarrow X$  are equal, the fixed point is at half the population size. Makes sense!

- Next week (18th July) is our last session
- (But there will still be a workshop on the 25th)
- Remember: Portfolio deadline is **1ST AUGUST**
- There's a new Portfolio Exercise on ILIAS
- And there will be one more next week, and that's it
- Any questions?